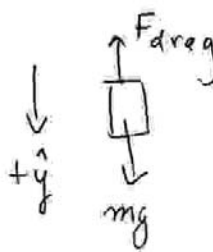


## Practice Exam 3 Solutions

Problem 1:



$$\begin{array}{c|c} F_y = m a_y & a_y = 0 \text{ since } (v_y)_{\text{term}} \text{ is a constant!} \\ \hline mg - F_{\text{drag}} = 0 & \\ \hline mg = F_{\text{drag}} & \end{array}$$

a)  $d = v_{\text{term}} t \Rightarrow t = \frac{d}{v_{\text{term}}} = \frac{1.6 \text{ km}}{5.0 \times 10^1 \text{ m/s}} = 32 \text{ s}$

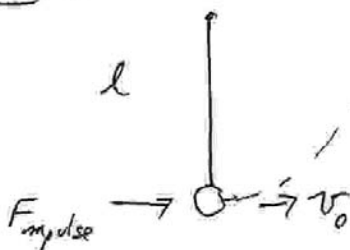
b)  $W_{\text{grav}} = mgd = (80 \times 10^1 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2})(1.6 \times 10^3 \text{ m}) = 1.25 \times 10^6 \text{ J}$

c)  $W_{\text{drag}} = -F_{\text{drag}} d = -mgd = -1.25 \times 10^6 \text{ J}$

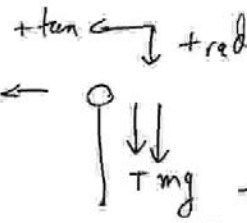
d)  $P_{\text{drag}} = \frac{W_{\text{drag}}}{t} = \frac{-mgd}{t} = \frac{-1.25 \times 10^6 \text{ J}}{3.2 \times 10^1 \text{ s}} = -3.92 \times 10^4 \text{ W}$

e)  $E_{\text{drag}} = W_{\text{drag}} = -mgd = -3.92 \times 10^4 \text{ J}$ . This energy shows up as heat; heating both the skydiver and the air.

Problem 3:



Free-body diagram at the end of the arc:



$$\begin{array}{c|c} F_{\text{rad}} = m a_{\text{rad}} & \\ \hline (1) \quad T + mg = \frac{mv_f^2}{l} & \end{array}$$

a)

Med. Energy is conserved since  $T$  is always perpendicular to the displacement

$$\Delta K + \Delta P.E. = W_{n.c.}$$


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$$\frac{1}{2} m(v_f^2 - v_o^2) + mg(2L) = 0$$

solving for  $v_f^2 = v_o^2 - 2g(2L)$

$$v_f = \left( (7.0 \text{ m/s})^2 - (2)(9.8 \frac{\text{m}}{\text{s}^2})(2)(.5 \text{ m}) \right)^{1/2} = 5.4 \frac{\text{m}}{\text{s}}$$

$$b) T = \frac{mv_f^2}{L} - mg = \frac{m(v_o^2 - 2g(2L))}{L} - mg$$

$$T = \frac{mv_o^2}{L} - 5mg = \frac{(.1 \text{ kg})(7.0 \frac{\text{m}}{\text{s}})^2}{(.5 \text{ m})} - (5)(.1 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2})$$

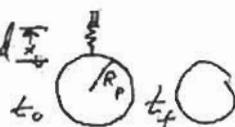
$$T = 4.9 \text{ N}$$

Problem 3:

the pen should have zero velocity at  $\infty$

a)

compressed  $\frac{x}{R_p}$



Energy is conserved

$$x_o \neq 0 \quad x_f = 0$$

$$v_o = 0 \quad v_f = 0$$

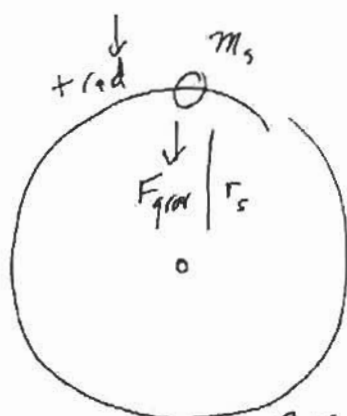
$$\Delta K + \Delta P.E. = W_{n.c.}$$


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$$0 + \frac{1}{2} k(x_f^2 - x_o^2) - Gm_1 m_2 \left( \frac{1}{\infty} - \frac{1}{R_p} \right) = 0$$

$$-\frac{1}{2} k x_o^2 + \frac{Gm_1 m_2}{R_p} = 0 \Rightarrow x_o^2 = \frac{2Gm_1 m_2}{R_p k}$$

$$x_o = \left( \frac{(2)(6.67 \times 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2})(.01 \text{ kg})(2.6 \times 10^{-5} \text{ kg})}{(5.0 \times 10^{-3} \text{ m})(400 \text{ N/m})} \right)^{1/2} = .042 \text{ m} = 4.2 \text{ cm}$$



$$\frac{F_{\text{rod}}}{\frac{G m_s m_p}{r_s^2}} = \frac{m_s a_{\text{rod}}}{m_s r_s \left( \frac{2\pi}{T} \right)^2}$$

solve for

$$r_s^3 = \frac{G m_p T^2}{4\pi^2}$$

$$r_s = \left( \frac{(6.67 \times 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2}) (2.6 \times 10^{15} \text{ kg}) ((2)(3.6 \times 10^3 \text{ sec}))^2}{4\pi^2} \right)^{1/3}$$

$$r_s = 6.1 \times 10^3 \text{ m}$$

$$v_s = \frac{2\pi r_s}{T} = \frac{(2\pi)(6.1 \times 10^3 \text{ m})}{(7.2 \times 10^3 \text{ sec})} = 5.3 \text{ m/s}$$

d) At the radius  $r_s$ , the conservation of mechanical energy can be used to calculate the velocity of the pen



$$\begin{aligned} t_0, \quad v_0 &= 0 \\ x_0 &= 4.2 \text{ cm} \\ &\text{from part a)} \\ r_0 &= R_p \end{aligned}$$



$$\begin{aligned} t', \quad v' &\neq 0 \\ x_f &= 0 \\ r' &= r_s \\ &\text{from part c)} \end{aligned}$$

$$\frac{\Delta K + \Delta P.E.}{\frac{1}{2} m_2 v'^2 - \frac{1}{2} k x_0^2 - G m_1 m_2 \left( \frac{1}{r_s} - \frac{1}{R_p} \right)} = \frac{W_{nc}}{0} \quad (1)$$

recall (from part a) that

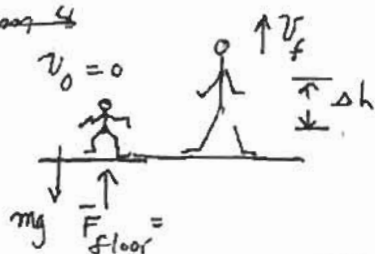
$$\frac{1}{2} k x_0^2 = \frac{G m_1 m_2}{R_p}$$

So eq (1) becomes  $\frac{1}{2} m_2 v'^2 - \frac{G m_1 m_2}{r_s} = 0$

$$v' = \left( \frac{2 G m_1}{r_s} \right)^{1/2} = \left( \frac{(2)(6.67 \times 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2}) (2.6 \times 10^{15} \text{ kg})}{6.1 \times 10^3 \text{ m}} \right)^{1/2}$$

$$v' = 7.54 \text{ m/s}$$

Problem 4



solve for  $v_f$ :

$$\Delta K + \Delta P.E. = W_{nc}$$

$$\frac{1}{2} m v_f^2 + m g (\Delta h) = \bar{F}_{floor} \Delta h$$

$$\bar{F}_{floor} = 3 m g$$

$$v_f = \left( 2 \left( \frac{\bar{F}_{floor} - m g}{m} \right) \Delta h \right)^{1/2} = \left( \frac{(2)(2 m g) \Delta h}{m} \right)^{1/2}$$

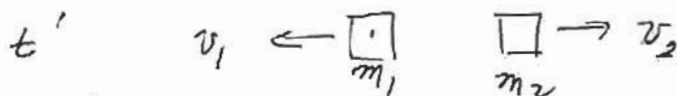
$$v_f = (2) (g \Delta h)^{1/2} = (2) \left( \left( \frac{9.8 m}{s^2} \right) (0.2 m) \right)^{1/2} = 2.8 \frac{m}{s}$$

Problem 5  $\Delta Q = m C_w \Delta T$

$$= (25 kg) \left( \frac{4190 J}{kg \cdot K} \right) (28 K) = 2.9 \times 10^4 J$$

$$b) P_{ave} = \frac{\Delta Q}{\Delta t} = \frac{2.9 \times 10^4 J}{60 s} = 4.9 \times 10^2 W$$

Problem 6:



momentum is conserved because there are no external forces. energy is not conserved due to the explosion.

$$\Delta p_x = 0$$

$$m_2 v_2 - m_1 v_1 = m v = 0$$

$$v_2 = \frac{m v + m_1 v_1}{m_2} = \frac{(2.0 kg) \left( \frac{2.0 m}{s} \right) + (0.5 kg) \left( \frac{1.0 \times 10^1 m}{s} \right)}{(1.5 kg)}$$

$$= 6 m/s$$

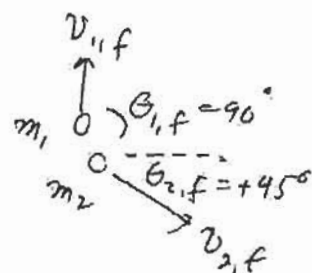
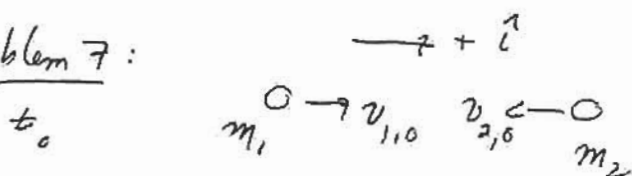
$$\Delta K_f = W_{n.c}$$

$$\frac{1}{2} m_2 v_2^2 + \frac{1}{2} m_1 v_1^2 - \frac{1}{2} m v^2 = W_{n.c.}$$

$$\left(\frac{1}{2}\right)(1.5 \text{ kg})\left(\frac{6 \text{ m}}{\text{s}}\right)^2 + \left(\frac{1}{2}\right)(.5 \text{ kg})\left(\frac{10 \text{ m}}{\text{s}}\right)^2 - \frac{1}{2}(2.0 \text{ kg})\left(\frac{2.0 \text{ m}}{\text{s}}\right)^2 = 48 \text{ J}$$

is the increase in kinetic energy due to the explosion.

Problem 7:



$$\Delta p_x = 0 \Rightarrow p_{x,i} = p_{x,f}$$

$$m_1 v_{1,i} - m_2 v_{2,i} = m_2 v_{2,f} \cos \theta_{2,f} \quad (1)$$

$$\Delta p_y = 0 \Rightarrow p_{y,i} = p_{y,f}$$

$$0 = m_1 v_{1,f} - m_2 v_{2,f} \sin \theta_{2,f} \quad (2)$$

$$\Delta K = 0 \Rightarrow K_i = K_f$$

$$\frac{1}{2} m_1 v_{1,i}^2 + \frac{1}{2} m_2 v_{2,i}^2 = \frac{1}{2} m_1 v_{1,f}^2 + \frac{1}{2} m_2 v_{2,f}^2 \quad (3)$$

Additionally - we are told that  $v_{1,f} = \frac{v_{1,i}}{2}$

eq (2) can be rewritten using this fact as

$$m_2 v_{2,f} \sin \theta_{2,f} = \frac{m_1 v_{1,i}}{2}$$

eq (1)  $m_2 v_{2,f} \cos \theta_{2,f} = m_1 v_{1,i} - m_2 v_{2,i}$

So dividing these equations yields

$$\tan \theta_{2,f} = \frac{m_1 v_{1,i} / 2}{m_1 v_{1,i} - m_2 v_{2,i}}$$

since  $\tan \theta_{2,f} = \tan 45^\circ = 1$  we have b

$$1 = \frac{m_1 v_{1,0} / 2}{m_1 v_{1,0} - m_2 v_{2,0}} \quad \text{or} \quad m_1 v_{1,0} - m_2 v_{2,0} = \frac{1}{2} m_1 v_{1,0}$$

which we can solve for  $v_{2,0}$

$$v_{2,0} = \frac{1}{2} \frac{m_1}{m_2} v_{1,0}$$

eq (2) can also be solved for  $v_{2,f}$

$$v_{2,f} = \frac{m_1}{m_2} \frac{v_{1,0}}{2} \sin \theta_{2,f} = \frac{m_1}{m_2} \frac{v_{1,0}}{2\sqrt{2}} = \frac{m_1}{m_2} \frac{v_{1,0}}{\sqrt{2}}$$

So eq (3), can be rewritten as

$$\frac{1}{2} m_1 v_{1,0}^2 + \frac{1}{2} m_2 \left( \frac{1}{2} \frac{m_1}{m_2} v_{1,0} \right)^2 = \frac{1}{2} m_1 \left( \frac{v_{1,0}}{2} \right)^2 + \frac{1}{2} m_2 \left( \frac{m_1}{m_2} \frac{v_{1,0}}{\sqrt{2}} \right)^2$$

or

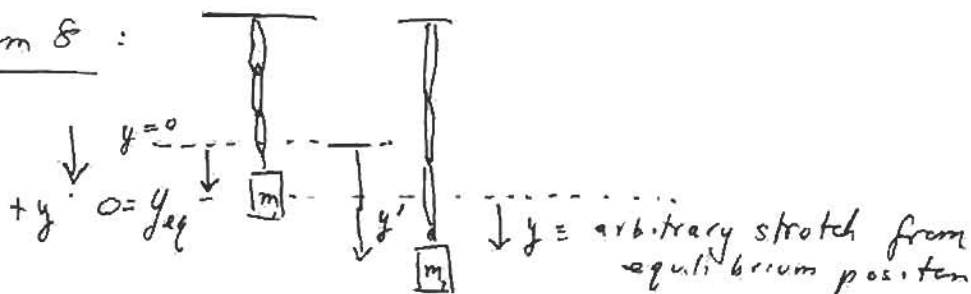
$$\frac{1}{2} m_1 v_{1,0}^2 + \frac{1}{2} m_2 \frac{1}{4} \frac{m_1^2}{m_2^2} v_{1,0}^2 = \frac{1}{2} m_1 \frac{v_{1,0}^2}{4} + \frac{1}{2} m_2 \frac{m_1^2}{m_2^2} \frac{v_{1,0}^2}{2}$$

$$\frac{3}{4} m_1 v_{1,0}^2 = \frac{1}{4} \frac{m_1^2}{m_2} v_{1,0}^2$$

$$\Rightarrow \boxed{3 = \frac{m_1}{m_2}}$$

Problem 8 :

7



The equilibrium position is already a slightly stretched position since at equilibrium

$$F_{\text{spring}} = m a_y$$

$$m g - k y_{eq} = 0 \Rightarrow y_{eq} = \frac{m g}{k}$$

$\downarrow$

Then when the system is stretched an additional distance  $y_0$  at  $t=0$

$$F_y = m a_y$$

$$m g - k(y + y_{eq}) = m \frac{d^2 y}{dt^2}$$

$$\underbrace{m g - k y_{eq}}_0 - k y = m \frac{d^2 y}{dt^2}$$

$$m \frac{d^2 y}{dt^2} + k y = 0$$

here  $y$  is an arbitrary stretch from eq. pos we get simple harmonic motion about  $y_{eq}$  position

$$y = A \cos \sqrt{\frac{k}{m}} t + B \sin \sqrt{\frac{k}{m}} t$$

$A = y_0$ ,  $B = \frac{v_0}{\sqrt{k/m}} = 0$  released from rest

$$v = \frac{dy}{dt} = -\sqrt{\frac{k}{m}} A \sin \sqrt{\frac{k}{m}} t + \sqrt{\frac{k}{m}} B \cos \sqrt{\frac{k}{m}} t$$

period  $T = \frac{2\pi}{\sqrt{k/m}} \Rightarrow T = 2\pi \sqrt{\frac{m}{k}}$

we can find the velocity using

$$y = y_0 \cos \sqrt{\frac{k}{m_1}} t,$$

$$v_y = -\sqrt{\frac{k}{m_1}} y_0 \sin \sqrt{\frac{k}{m_1}} t$$

noting that when  $\sqrt{\frac{k}{m_1}} t = \pi/2$ ,  $\cos(\sqrt{\frac{k}{m_1}} t) = 0$   
so  $y = 0$ , mass is back at eq. pos.

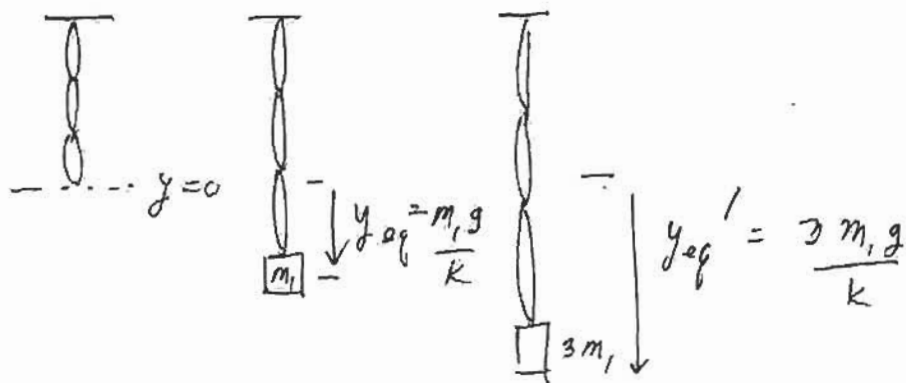
Also,  $\sin(\frac{\pi}{2}) = 1$  so

$$v_y = -\sqrt{\frac{k}{m_1}} y_0 \text{ at eq. pos. } t_{eq} = \frac{\pi}{2} \sqrt{\frac{m_1}{k}}$$

c) since a new mass  $m_2 = 2m_1$ ,  
 $m_{total} = 3m_1$ , and  $T = 2\pi \sqrt{\frac{3m_1}{k}}$

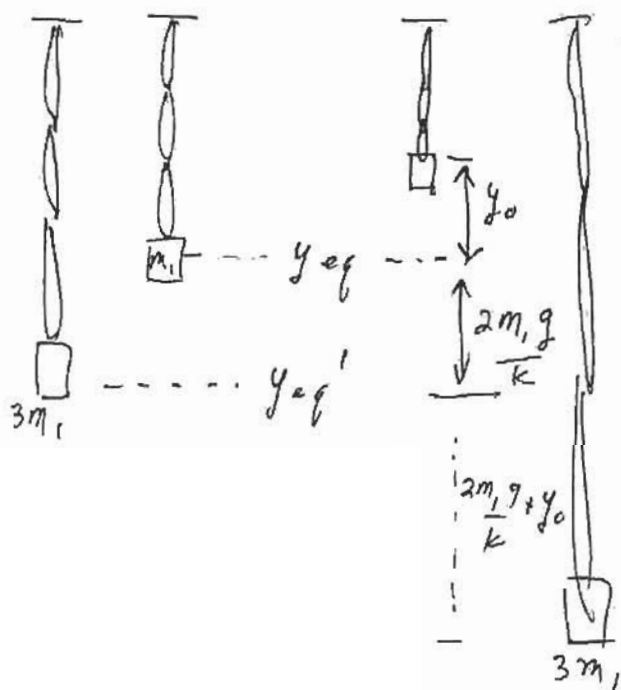
d) since the collision occurred when  
the mass was completely compressed,  
the velocity was zero, hence for  
the collision  $\Delta K = 0$ , no energy  
was lost. therefore, the new system  
of mass  $3m_1$  will satisfy  
a new equilibrium condition  
 $3m_1 g = k y_{eq'} \Rightarrow y_{eq'} = 3m_1 g / k$   
and the oscillations are about this position.





So the new equilibrium position is lowered by  $\frac{2m_1 g}{k}$

When the rubber bands were fully compressed by  $y_0$ , the collision occurred. The



so with respect to the new equilibrium position the stretch is

$$y_0 + \frac{2m_1 g}{k}$$

Hence when the system is fully stretched, the mass  $3m_1$  is at a position

$$y_0 + \frac{4m_1 g}{k} \text{ from}$$

the original equilibrium position