

$$\sigma_s(\nu) = \frac{\sigma_{so}}{\beta^2} \left[\left(\beta^2 + \frac{1}{2} \right) \text{erf}(\beta) + \frac{1}{\sqrt{\pi}} \beta e^{-\beta^2} \right]$$

$$\frac{d\sigma_C}{d\Omega} = \frac{r_e^2}{4} \left(\frac{\omega'}{\omega} \right)^2 \left[\frac{\omega}{\omega'} + \frac{\omega'}{\omega} - 2 + 4 \cos^2 \Theta \right]$$

$$\frac{d\sigma_C}{d\Omega} = \frac{r_e^2}{2} (1 + \cos^2 \theta) \left(\frac{1}{1 + \alpha(1 - \cos \theta)} \right)^2 \left[1 + \frac{\alpha^2 (1 - \cos \theta)^2}{(1 + \cos^2 \theta)[1 + \alpha(1 - \cos \theta)]} \right]$$

$$\frac{d\sigma_\tau}{d\Omega} = 4\sqrt{2} \frac{r_e^2 Z^5}{(137)^4} \left(\frac{m_e c^2}{\hbar \omega} \right)^{7/2} \frac{\sin^2 \theta \cos^2 \varphi}{\left(1 - \frac{\nu}{c} \cos \theta \right)^4}$$

$$\frac{d\sigma_\kappa}{dT_+} = 4\sigma_o Z^2 \frac{T_+^2 + T_-^2 - \frac{2}{3} T_+ T_-}{(\hbar \omega)^3} \left[\ell n \left(\frac{2T_+ T_-}{\hbar \omega m_e c^2} \right) - \frac{1}{2} \right]$$

$$Q = T_3 \left(1 + \frac{M_3}{M_4} \right) - T_1 \left(1 - \frac{M_1}{M_4} \right) - \frac{2}{M_4} (M_1 M_3 T_1 T_3)^{1/2} \cos \theta$$

$$\sigma_C(T_i) = \pi \tilde{\lambda}^2 g_J \frac{\Gamma_a \Gamma}{(T_i - T_i^*)^2 + \Gamma^2 / 4}$$

$$\gamma = \frac{8Z_D e^2}{\hbar \nu} \left[\cos^{-1} \sqrt{y} - \sqrt{y(1-y)}^{1/2} \right]$$

$$\sigma(n, n) = 4\pi a^2 + \pi \tilde{\lambda}^2 g_J \frac{\Gamma_n^2}{(T_i - T_i^*)^2 + \Gamma^2 / 4} + 4\pi \tilde{\lambda} g_J a \Gamma_n \frac{(T_i - T_i^*)}{(T_i - T_i^*)^2 + \Gamma^2 / 4}$$