

# Chapter 6

## Computerized tomography

### 6.1 Assumptions and vocabulary

(...)

Computerized tomography (CT scans, as well as PET scans) imaging involves inversion of a Radon or X-ray transform. It is primarily used for medical imaging.

In two spatial dimensions, the variables in the Radon domain are  $t$  (offset) and  $\theta$  (angle). Data in the form  $d(t, \theta)$  corresponds to the *parallel beam* geometry. More often, data follow the *fan-beam* geometry, where for a given value of  $\theta$  the rays intersect at a point (the source of X-rays), and  $t$  indexes rays within the fan. The transformation to go from parallel-beam to fan-beam and back is

$$d_{\text{fan}}(t, \theta) = d_{\text{para}}(t, \theta + (at + b)),$$

for some numbers  $a$  and  $b$  that depend on the acquisition geometry. Datasets in the Radon domain are in practice called *sinograms*, because the Radon transform of a Dirac mass is a sine wave<sup>1</sup>.

### 6.2 The Radon transform and its inverse

Radon transform:

$$(Rf)(t, \theta) = \int \delta(t - x \cdot e_\theta) f(x) dx,$$

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<sup>1</sup>More precisely, a distribution supported on the graph of a sine wave, see an exercise at the end of the chapter.

with  $e_\theta = (\cos \theta, \sin \theta)^T$ .

Fourier transform in  $t$  / Fourier-slice theorem<sup>2</sup>:

$$\widehat{Rf}(\omega, \theta) = \int e^{-i\omega x \cdot e_\theta} f(x) dx.$$

Adjoint Radon transform / (unfiltered) backprojection:

$$\begin{aligned} R^*d(x) &= \int e^{i\omega x \cdot e_\theta} \widehat{d}(\omega, \theta) d\omega d\theta \\ &= \int \delta(t - x \cdot e_\theta) d(t, \theta) dt d\theta \\ &= \int d(x \cdot \theta, \theta) d\theta \end{aligned}$$

Inverse Radon transform / filtered backprojection in the case of two spatial dimensions:

$$R^{-1}d(x) = \frac{1}{(2\pi)^n} \int e^{i\omega x \cdot e_\theta} \widehat{d}(\omega, \theta) \omega d\omega d\theta.$$

(notice the factor  $\omega$ .)

Filtered backprojection can be computed by the following sequence of steps:

- Take a Fourier transform to pass from  $t$  to  $\omega$ ;
- Multiply by  $\omega$ ;
- Take an inverse Fourier transform from  $\omega$  back to  $t$ , call  $D(t, \theta)$  the result;
- Compute  $\int d(x \cdot \theta, \theta) d\theta$  by quadrature and interpolation (piecewise linear interpolation is often accurate enough.)

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<sup>2</sup>The direct Fourier transform comes with  $e^{-i\omega t}$ . Here  $t$  is offset, not time, so we use the usual convention for the FT.

## 6.3 Exercises

1. Compute the Radon transform of a Dirac mass, and show that it is nonzero along a sinusoidal curve (with independent variable  $\theta$  and dependent variable  $t$ , and wavelength  $2\pi$ .)
2. In this problem set we will form an image from a fan-beam CT dataset. (Courtesy Frank Natterer)

Download the data set at <http://math.mit.edu/icg/ct.mat>

and load it in MATLAB<sup>®</sup> with `load ct.mat`

The array  $g$  is a sinogram. It has 513 rows, corresponding to uniformly sampled offsets  $t$ , and 360 columns, corresponding to uniform, all-around angular sampling with 1-degree steps in  $\theta$ . The acquisition is fan-beam: a transformation is needed to recover the parallel-beam geometry. The fan-beam geometry manifests itself in that the angle depends on the offset  $t$  in a linear fashion. Instead of being just  $\theta$ , it is ( $1 \leq t \leq 513$  is the row index)

$$\theta + \frac{t - 257}{256}\alpha,$$

with

$$\sin \alpha = \frac{1}{2.87}.$$

Imaging from a parallel-beam sinogram is done by filtered backprojection. Filtering is multiplication by  $\omega$  in the  $\omega$  domain dual to the offset  $t$ . Backprojection of a sinogram  $g(t, \theta)$  is

$$I(x) = \sum_{\theta} g(x \cdot \mathbf{e}_{\theta}, \theta),$$

where  $\mathbf{e}_{\theta}$  is  $(\cos \theta, \sin \theta)^T$ . Form the image on a grid which has at least 100 by 100 grid points (preferably 200 by 200). You will need an interpolation routine since  $x \cdot \mathbf{e}_{\theta}$  may not be an integer; piecewise linear interpolation is accurate enough (`interp1` in MATLAB).

In your writeup, show your best image, your code, and write no more than one page to explain your choices.



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18.325 Topics in Applied Mathematics: Waves and Imaging  
Fall 2012

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