

MIT OpenCourseWare  
<http://ocw.mit.edu>

6.189 Multicore Programming Primer, January (IAP) 2007

Please use the following citation format:

Mike Acton, *6.189 Multicore Programming Primer, January (IAP) 2007*.  
(Massachusetts Institute of Technology: MIT OpenCourseWare).  
<http://ocw.mit.edu> (accessed MM DD, YYYY). License: Creative  
Commons Attribution-Noncommercial-Share Alike.

Note: Please use the actual date you accessed this material in your citation.

For more information about citing these materials or our Terms of Use, visit:  
<http://ocw.mit.edu/terms>

# 6.189 IAP 2007

---

## Lecture 16

### Introduction to Game Development

# *Introduction to Game Development (on the Playstation 3 / Cell )*

- Mike Acton
  - Engine Director, Insomniac Games
  - Director, CellPerformance.com



# *Different Types of Game Development*

- Casual
  - Console
  - PC
  - Handheld
  - Cellphone
  - Single Player
  - Multi Player
- 
-

# *Console Development Priorities*

- The code itself is not that important.
  - The design of the data affects performance more than the design of the code.
  - Ease of programming is either a minor or non-priority.
  - Portability is not a concern.
  - Performance is still king.
- 
-

# *Development Team*

- Artists
    - Animation, Shader, Texture, Modeling
    - Environment, Lighting, ...
  - Designers
    - Systems, Level, ...
  - Writers
  - Producers
  - Programmers
    - Gameplay, Engine, AI, Special Effects,
    - Sound/Music, ...
- 
-

# *What Impacts Game's Technical Design?*

- Type of game
- Framerate
- Schedule
- Cost
- Hardware
- Compilers
- ...
- How does this affect code reusability?
- How does this affect cross-platform design?



# *What are the major game modules?*

- Memory management
  - Math
  - Collision
  - Physics
  - Static graphics
  - Animation
  - Procedural graphics
  - Lighting
  - Loading, streaming
  - Scene graph
  - AI
  - Compression
  - Sound, Music
  - Special Effects
  - State machines
  - Scripting
  - Motion control
  - ...
- 
-



# Overview

- How does programming on the Playstation 3 affect the (macro) design of the major systems?
- Overview of design process for a specific system (Animation).



# *Structure Design (1)*

- Conventional structures are (surprisingly?) needed very little in engine-level SPU code.
  - Data is compressed
  - Data is sorted by type (i.e. Fewer flags)
  - Data is organized into blocks or streams
  - Data is accessed only in quadwords



# *Structure Design (2)*

- Organize data carefully:
    - Prefer fixed (known) size blocks
    - Fundamental unit: 128 bytes (Cache line)
    - Fundamental unit: 16 bytes (Quadword)
    - Prefer uniform data
  - Minimum working sizes:
    - 4 x 2 x 64 bits
    - 4 x 4 x 32 bits
    - 4 x 8 x 16 bits
    - 4 x 16 x 8 bits
    - 4 x 128 bits
- 
-

# *Basic Math*

- e.g. Vector Class
  - Usually the first thing a programmer will make, but consider:
    - SIMD, AltiVec vs. SPU instruction set
    - Floats vs. Double vs. Fixed-point
    - SPU floating-point format
    - Component access
  - ... There's no value here.



# *Memory Manager*

- Static allocation is preferred to dynamic
  - Most data patterns are known in advance
  - When designing allocator, consider:
    - Page sizes
    - LRU is most common, but pretty bad.
    - Hierarchy of allocations
    - Fragmentation is a non-issue for well planned architectures
    - Remember cache line alignment.
    - SPU transfer blocks, 16K
- 
-

# *Collision Detection*

- Affects high-level design
  - Deferred results
  - Grouped results
- SPU decomposition for:
  - Static geometry in scene
  - Dynamic geometry in scene



# *Procedural Graphics*

- Patch size
- Filter types
- Sync of source reads
- Sync with GPU
- SPU vs. RSX
- Particles
- Cloth
- Fonts
- Textures
- Parametric geometry
- ...



# *Geometry databases*

- No scene graph
- Domain information linked by key
- Cache and TLB affect design choices
  - e.g. Static geometry lookup (Octree, BSP, etc.)
- Geometry lookups on SPU
  - Spatially pre-sort
  - Multiple simultaneous lookups





# *Game Logic*

- State machines
    - Size affected by SPU
    - Deferred results
    - Logic lines can be deferred
  - Scripting
    - Interpreter size
    - Multiple streams to hide memory accesses
  - Motion control
    - High-level sync (Animation, AI, Physics)
- 
-

# Animation (1)

- Starting with the basics:
  - Simple playback, animation channels
    - Related data
    - e.g. Rotation + Translation + Scale = Joint
  - Euler vs. quaternion
    - Euler: More compressible
    - Quaternion: Less messy
    - Gimbal lock is manageable in practice.
  - Format, double vs. float vs. half vs. fixed-point
  - Rotations: Degrees, radians or normalized?

# *Animation (2)*

- Animation frame storage
  - Basic 9 channels (raw)
  - Uniform channels
    - Plus uniform channel map
    - Plus uniform channel count
  - X Number of joints
  - Decide on max channels



# *Animation (3)*

- Channel curve fitting
  - Closer to root, tighter fit.
  - e.g. Simple spline
    - Store time values
    - Problem: Looping scalars
    - Problem: Unlimited length



# *Animation (4)*

- e.g. Spline segments
  - Plus storage for time maps
  - Plus segment lookup time
  - Advantage: Can re-order blocks
  - Advantage: Long lengths OK
  - Disadvantage: Less compressable
  - Advantage: Solves scalar loop problem
- Summarize: DMA and transform.



# *Animation (5)*

- e.g. Adding dynamic channel support
  - Add uniform data table
    - Maximum dynamic channels with linkage, or...
    - All uncompressed
  - Add (simple) constraints
    - Max change
    - Max range
    - Max acceleration (impacts storage)
  - Blend information
  - Summarize: DMA and transform.



# *Animation (6)*

- More on mixing:
  - Phase matching
  - Transitions
  - Translation matching
- Drawing animated geometry
  - Single or double buffer joints:
    - Single: Requires more organization
    - Double: More memory, more flexible.



# *Optimization*

- Required for practice
- Impacts design
- NOT the root of all evil

