

$H^{\text{SO}} + H^{\text{Zeeman}}$ Coupled vs. Uncoupled Basis Sets

Last time:

matrices for \mathbf{J}^2 , \mathbf{J}_+ , \mathbf{J}_- , \mathbf{J}_z , \mathbf{J}_x , \mathbf{J}_y in $|jm_j\rangle$ basis for $J = 0, 1/2, 1$

Pauli spin 1/2 matrices

arbitrary 2×2 $\mathbf{M} = a_0 \mathbf{I} + \vec{a}_1 \cdot \vec{\sigma}$

When \mathbf{M} is $\rho \rightarrow$ visualization of fictitious vector in fictitious B-field

When \mathbf{M} is a term in $\mathbf{H} \rightarrow$ idea that arbitrary operator can be decomposed as sum of \mathbf{J}_i .

types of operators

| | |
|-----------------------------------|---|
| $a\mathbf{J}$ | e.g. magnetic moment (a is a known constant or a function of r) |
| \vec{q} | how to evaluate matrix elements (e.g. Stark Effect) |
| $\mathbf{J}_1 \cdot \mathbf{J}_2$ | e.g. Spin - Orbit |

TODAY:

1. $H^{\text{SO}} + H^{\text{Zeeman}}$ as illustrative
2. Dimension of basis sets $|JL S M_J\rangle$ and $|L M_L S M_S\rangle$ is same
3. matrix elements of H^{SO} in both basis sets
4. matrix elements of H^{Zeeman} in both basis sets
5. ladders and orthogonality for transformation between basis sets. Necessary to be able to evaluate matrix elements of H^{Zeeman} in coupled basis. Why? Because coupled basis set does not explicitly give effects of \mathbf{L}_z or \mathbf{S}_z .

5.73 Lecture #25

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Suppose we have 2 kinds of angular momenta, which can be coupled to each other to form a *total* angular momentum.

$$\left. \begin{array}{ll} \vec{L} & \text{orbital} \\ \vec{S} & \text{spin} \\ \vec{J} = \vec{L} + \vec{S} & \text{total} \end{array} \right\} \text{operate on different coordinates or in different vector spaces}$$

The components of \mathbf{L} , \mathbf{S} , and \mathbf{J} each follow the standard angular momentum commutation rule, but

$$\begin{aligned} [\vec{L}, \vec{S}] &= 0, & [\mathbf{J}_i, \mathbf{L}_j] &= i\hbar \sum_k \epsilon_{ijk} \mathbf{L}_k \\ & & [\mathbf{J}_i, \mathbf{S}_j] &= i\hbar \sum_k \epsilon_{ijk} \mathbf{S}_k. \end{aligned}$$

These commutation rules specify that \mathbf{L} and \mathbf{S} act like vectors wrt \mathbf{J} but as scalars wrt to each other.

$$\begin{aligned} \vec{J} &\rightarrow |jm_j\rangle \\ \vec{L} &\rightarrow |\ell m_\ell\rangle \\ \vec{S} &\rightarrow |sm_s\rangle \end{aligned}$$

Coupled $|j\ell sm_j\rangle$ vs. *uncoupled* $|\ell m_\ell\rangle |sm_s\rangle$ representations.

- * matrix elements of certain operators are more convenient in one basis set than the other
- * a unitary transformation between basis sets must exist
- * limiting cases for energy level patterns

$$\begin{aligned} & \mathbf{H}^{\text{SO}} = \xi(r) \boldsymbol{\ell} \cdot \mathbf{s} \equiv \frac{\zeta_{nl}}{\hbar} \boldsymbol{\ell} \cdot \mathbf{s} \\ & \mathbf{H}^{\text{Zeeman}} = -\gamma B_z (\ell_z + 2s_z) \equiv -(\omega_0) (\ell_z + 2s_z) \end{aligned}$$

(ζ_{nl} and ω_0 are in rad / s)

(ℓ and s will each give a factor of \hbar)

(anomalous g - value of e^-)

(will give a factor of \hbar)

- * evaluate matrix elements in both basis sets
- * look at energy levels in high field $|\gamma B_z| \gg \zeta_{nl}$ limit
- * look at energy levels in low field $|\gamma B_z| \ll \zeta_{nl}$ limit

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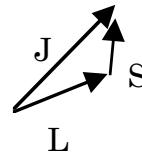
Notation: $\left\{ \begin{array}{l} \text{lower case for } 1e^- \text{ atom angular momenta} \\ \text{upper case for many-}e^- \text{ angular momenta} \end{array} \right.$

two different CSCOs

- | | | |
|---|-----------------------|---|
| a) $H^{\text{elect}}, J^2, J_z, \dots^2, S^2$ | coupled basis | } recall tensor product states and "entanglement" |
| $ nJLSM_J\rangle$ | (can be factored) | |
| b) $H^{\text{elect}}, \dots^2, \dots_z, S^2, S_z$ | uncoupled basis | } |
| $ nLM_L\rangle SM_S\rangle$ | (explicitly factored) | |

2. Coupled and Uncoupled Basis Sets Have Same Dimension

COUPLED $\vec{J} = \vec{L} + \vec{S} \quad |L - S| \leq J \leq L + S$
 each J has $2J + 1$ M_J 's



| | | |
|-------------|--------------------|---------------------------------------|
| $J = L + S$ | $2(L + S) + 1$ | every J contributes $2L + 1$ to sum |
| $L + S - 1$ | $2(L + S - 1) + 1$ | |
| $L + S - 2$ | $2(L + S - 2) + 1$ | |
| ... | ... | |
| | $2(L - S) + 1$ | |

If $L > S$, there are $2S + 1$ terms in sum

$$(2S + 1)(2L + 1) + \underbrace{2[S + (S - 1) + \dots + (-S)]}_{= 0} = \underbrace{(2S + 1)(2L + 1)}_{\uparrow}$$

total dimension of basis set for specified L, S

UNCOUPLED $\underbrace{LM_L}_{2L+1} \underbrace{SM_S}_{2S+1}$ total dimension $(2L + 1)(2S + 1)$ again

term for term correspondence between 2 basis sets
 \therefore a transformation must exist:

Coupled basis state in terms of uncoupled basis states:

$$|JLSM_J\rangle = \sum_{M_L} a_{M_L} |LM_L\rangle \underbrace{|SM_S = M_J - M_L\rangle}_{\text{constraint}}$$

Trade J, M_J for M_L, M_S , but $M_J = M_L + M_S$.

Uncoupled basis state in terms of coupled basis states:

$$\text{OR } |LM_J\rangle |SM_S\rangle = \sum_{J=|L-S|}^{L+S} b_J \left| \underbrace{JLSM_J = M_L + M_S}_{\text{constraint}} \right\rangle$$

3. Matrix elements of $\mathbf{H}^{SO} = \frac{\zeta_{nl}}{\hbar} \ell \cdot \mathbf{s}$

A. Coupled Representation

$$\vec{\mathbf{J}} = \vec{\mathbf{L}} + \vec{\mathbf{S}} \quad \mathbf{J}^2 = \mathbf{L}^2 + \mathbf{S}^2 + 2\mathbf{L} \cdot \mathbf{S}$$

$$\mathbf{L} \cdot \mathbf{S} = \frac{\mathbf{J}^2 - \mathbf{L}^2 - \mathbf{S}^2}{2} \quad \text{(useful trick!)}$$

$$\langle J'L'S'M_J | \mathbf{L} \cdot \mathbf{S} | JLSM_J \rangle = (\hbar^2/2) [J(J+1) - L(L+1) - S(S+1)] \delta_{J'J} \delta_{L'L} \delta_{S'S} \delta_{M'_J M_J}$$

a purely diagonal matrix.

B. Uncoupled Representation

$$\mathbf{L} \cdot \mathbf{S} = \underbrace{\mathbf{L}_z \mathbf{S}_z}_{\text{diagonal}} + \frac{1}{2} (\underbrace{\mathbf{L}_+ \mathbf{S}_- + \mathbf{L}_- \mathbf{S}_+}_{\text{off-diagonal}})$$

$$\langle L'M'_L S'M'_S | \mathbf{L} \cdot \mathbf{S} | LM_L SM_S \rangle = \hbar^2 \delta_{L'L} \delta_{S'S} \times$$

can't change L

can't change S

$$\left\{ [M'_L M'_S \delta_{M'_L M_L} \delta_{M'_S M_S}] + \frac{1}{2} [L(L+1) - M'_L M_L]^{1/2} \times \right.$$

$$\left. [S(S+1) - M'_S M_S]^{1/2} \delta_{M'_L M_L \pm 1} \times \delta_{M'_S M_S \mp 1} \right\} \quad \Delta M_L = -\Delta M_S = 0, \pm 1$$

Nonlecture notes for evaluated matrices

$$S = 1/2,$$

$$L = 0, 1, 2$$

$$\boxed{{}^2S, {}^2P, {}^2D \text{ states}}$$

$^{2S+1}L_J$ NONLECTURE for \mathbf{H}^{SO} : COUPLED BASIS

$^2S_{1/2}$ $\mathbf{H}_{COUPLED}^{SO} = \frac{\hbar}{2} \zeta_{ns}(0)$

2P $\mathbf{H}_{COUPLED}^{SO} = \frac{\hbar}{2} \zeta_{np}$

$$\begin{pmatrix} -2 & 0 & | & 0 & 0 & 0 & 0 \\ 0 & -2 & | & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & | & 1 & 0 & 0 & 0 \\ 0 & 0 & | & 0 & 1 & 0 & 0 \\ 0 & 0 & | & 0 & 0 & 1 & 0 \\ 0 & 0 & | & 0 & 0 & 0 & 1 \end{pmatrix} \begin{matrix} J = 1/2 \\ \\ J = 3/2 \end{matrix}$$

| | L | J | $J(J+1) - L(L+1) - S(S+1) =$ | | | |
|---------------|---|-----|------------------------------|---|-----|----|
| $(^2S_{1/2})$ | 0 | 1/2 | 3/4 | 0 | 3/4 | 0 |
| $(^2P_{1/2})$ | 1 | 1/2 | 3/4 | 2 | 3/4 | -2 |
| $(^2P_{3/2})$ | 1 | 3/2 | 15/4 | 2 | 3/4 | +1 |
| $(^2D_{3/2})$ | 2 | 3/2 | 15/4 | 6 | 3/4 | -3 |
| $(^2D_{5/2})$ | 2 | 5/2 | 35/4 | 6 | 3/4 | +2 |

$J = 3/2$

2D $\mathbf{H}_{COUPLED}^{SO} = \frac{\hbar}{2} \zeta_{nd}$

$$\begin{pmatrix} -3 & 0 & 0 & 0 & | & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -3 & 0 & 0 & | & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -3 & 0 & | & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -3 & | & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & | & 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & 0 & 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & 0 & 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 & | & 0 & 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & | & 0 & 0 & 0 & 0 & 0 & 2 \end{pmatrix}$$

$J = 5/2$

center of gravity rule: trace of matrix = 0
(obeyed for all *scalar* terms in \mathbf{H})

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$2S+1L$

NONLECTURE for H^{SO} : **UNCOUPLED BASIS**

$2S$

$$\mathbf{H}_{\text{UNCOUPLED}}^{\text{SO}} = \hbar\zeta_{ns}(1/2 \cdot 0) = (0)$$

$2P$

$$\mathbf{H}_{\text{UNCOUPLED}}^{\text{SO}} = \hbar\zeta_{np} \times$$

| M_L | M_S | | | | | | | | | |
|-------|-------|-----|------------|------------|---|------------|------------|---|-----|---|
| 1 | 1/2 | 1/2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | -1/2 | 0 | -1/2 | $2^{-1/2}$ | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 1/2 | 0 | $2^{-1/2}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | -1/2 | 0 | 0 | 0 | 0 | 0 | $2^{-1/2}$ | 0 | 0 | 0 |
| -1 | 1/2 | 0 | 0 | 0 | 0 | $2^{-1/2}$ | -1/2 | 0 | 0 | 0 |
| -1 | -1/2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1/2 | 0 |

Each box is for one value of $M_J = M_L + M_S$.

$2D$

$$\mathbf{H}_{\text{UNCOUPLED}}^{\text{SO}} = \hbar\zeta_{nd} \times$$

M_L

M_S

| | | | | | | | | | | | | | | |
|----|------|---|----|-----|---------------|---------------|---------------|---------------|-----|----|---|---|---|---|
| 2 | 1/2 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 2 | -1/2 | 0 | -1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 1/2 | 0 | 1 | 1/2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | -1/2 | 0 | 0 | 0 | -1/2 | $(3/2)^{1/2}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 1/2 | 0 | 0 | 0 | $(3/2)^{1/2}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | -1/2 | 0 | 0 | 0 | 0 | 0 | 0 | $(3/2)^{1/2}$ | 0 | 0 | 0 | 0 | 0 | 0 |
| -1 | 1/2 | 0 | 0 | 0 | 0 | 0 | $(3/2)^{1/2}$ | -1/2 | 0 | 0 | 0 | 0 | 0 | 0 |
| -1 | -1/2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1/2 | 1 | 0 | 0 | 0 | 0 |
| -2 | 1/2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | -1 | 0 | 0 | 0 | 0 |
| -2 | -1/2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |

4. Matrix Elements of $\mathbf{H}^{\text{Zeeman}} = -\gamma\mathbf{B}_z(\mathbf{L}_z + 2\mathbf{S}_z)$

A. very easy in uncoupled representation

$$\begin{aligned} \mathbf{H}_{\text{uncoupled}}^{\text{Zeeman}} &= -\gamma\mathbf{B}_z \langle \mathbf{L}'M'_L \mathbf{S}'M'_S | \mathbf{L}_z + 2\mathbf{S}_z | \mathbf{L}M_L \mathbf{S}M_S \rangle \\ &= -\gamma\mathbf{B}_z \hbar (M_L + 2M_S) \delta_{L'L} \delta_{S'S} \delta_{M'_L M_L} \delta_{M'_S M_S} \end{aligned}$$

strictly diagonal

B. coupled representation

$$\mathbf{L}_z + 2\mathbf{S}_z = \underbrace{\mathbf{J}_z}_{\text{easy}} + \underbrace{\mathbf{S}_z}_{\text{hard — no clue!}}$$

can't evaluate matrix elements in coupled representation without a new trick

5. If we wish to work in *coupled* representation, because it diagonalizes \mathbf{H}^{SO} , need to find transformation

$$|JLSM_J\rangle = \sum_{M_L} a_{M_L} |LM_L SM_S = M_J - M_L\rangle$$

lengthy procedure: $\mathbf{J}_{\pm} = \mathbf{L}_{\pm} + \mathbf{S}_{\pm}$ and orthogonality

Always start with an extreme M_L, M_S basis state, where we are assured of a trivial correspondence between basis sets:

$$\begin{aligned} M_L = L, \quad M_S = S, \quad M_J = M_L + M_S = L + S, \quad J = L + S \\ |J = L + S \quad LSM_J = L + S\rangle = |LM_L = L \quad SM_S = S\rangle \\ \text{coupled} \qquad \qquad \qquad \text{uncoupled} \end{aligned}$$

$$\mathbf{J}_- |\overbrace{L+S}^J \overbrace{LS}^{\quad} \overbrace{L+S}^{M_J}\rangle = (\mathbf{L}_- + \mathbf{S}_-) |LM_L = L \quad SM_S = S\rangle$$

$$\begin{bmatrix} (L+S)(L+S+1) \\ -(L+S)(L+S-1) \end{bmatrix}^{1/2} |L+S \quad LS \quad L+S-1\rangle = [L(L+1) - L(L-1)]^{1/2} |LL-1SS\rangle \\ + [S(S+1) - S(S-1)]^{1/2} |LLSS-1\rangle$$

Thus we have derived a specific linear combination of 2 uncoupled basis states.

There is only one other orthogonal linear combination belonging to the same value of $M_L + M_S = M_J$: it must belong to the $\frac{|L+S-1\rangle}{\text{lower J}} \quad LS \quad L+S-1\rangle$ basis state.

NONLECTURE

Work this out for 2P

$$|JLSM_J\rangle = |3/2 \quad 1 \quad 1/2 \quad 3/2\rangle = |LM_L SM_S\rangle = |1 \quad 1 \quad 1/2 \quad 1/2\rangle \\ |JLSM_J-1\rangle = \frac{2^{1/2}|1 \quad 0 \quad 1/2 \quad 1/2\rangle + |1 \quad 1 \quad 1/2 \quad -1/2\rangle}{3^{1/2}}$$

now use orthogonality:

$$|J-1LSM_J-1\rangle = |1/2 \quad 1 \quad 1/2 \quad 1/2\rangle = \frac{-|1 \quad 0 \quad 1/2 \quad 1/2\rangle + 2^{1/2}|1 \quad 1 \quad 1/2 \quad -1/2\rangle}{3^{1/2}}$$

Continue laddering down to get all 4 $J = 3/2$ and all 2 $J = 1/2$ basis states.

$$|3/2 \quad 1 \quad 1/2 \quad -1/2\rangle = \left(\frac{2}{3}\right)^{1/2} |1 \quad 0 \quad 1/2 \quad -1/2\rangle + \left(\frac{1}{3}\right)^{1/2} |1 \quad -1 \quad 1/2 \quad 1/2\rangle \\ |3/2 \quad 1 \quad 1/2 \quad -3/2\rangle = |1 \quad -1 \quad 1/2 \quad -1/2\rangle \\ |1/2 \quad 1 \quad 1/2 \quad 1/2\rangle = -\left(\frac{1}{3}\right)^{1/2} |1 \quad 0 \quad 1/2 \quad -1/2\rangle + \left(\frac{2}{3}\right)^{1/2} |1 \quad -1 \quad 1/2 \quad 1/2\rangle$$

You work out the transformation for 2D !

Next step will be to evaluate $\mathbf{H}^{\text{SO}} + \mathbf{H}^{\text{Zeeman}}$ in both coupled and uncoupled basis sets and look for limiting behavior.